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Signed graphs whose all Laplacian eigenvalues are main

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Signed graphs whose all Laplacian eigenvalues

- For a graph G we consider the problem of the existence of a switching equivalent signed graph with Laplacian eigenvalues that are all main and the problem of determination of all switching equivalent signed graphs with this spectral property.
- Using a computer search we confirm that apart from K₂ every connected graph with at most 7 vertices switches to at least one signed graph with the required property. This fails to hold for exactly 22 connected graphs with 8 vertices.
- If G is a cograph without repeated eigenvalues, then we give an iterative solution and the complete solution in the particular case when G is a threshold graph.

- Given a graph G = (V(G), E(G)), let $\sigma \colon E(G) \longrightarrow \{1, -1\}$. Then $\dot{G} = (G, \sigma)$ is a signed graph derived from its underlying graph G.
- The adjacency matrix $A_{\dot{G}}$ of \dot{G} is obtained from the (0, 1)-adjacency matrix of the underlying graph G by reversing the sign of all 1s which correspond to negative edges.
- The Laplacian matrix of \dot{G} is defined by $L_{\dot{G}} = D_{\dot{G}} A_{\dot{G}}$, where $D_{\dot{G}}$ is the diagonal matrix of vertex degrees.
- The eigenvalues and the spectrum of \dot{G} are identified to be the eigenvalues and the spectrum of $A_{\dot{G}}$, while the Laplacian eigenvalues and the Laplacian spectrum of \dot{G} refer to the eigenvalues and the spectrum of $L_{\dot{G}}$.

Switching equivalent signed graphs

- We say that the signed graphs G and H are switching equivalent if there is a vertex subset U ⊆ V(G) such that H is obtained by reversing the sign of every edge with one end in U and the other in V(G) \ U.
- The underlying graphs of switching equivalent signed graphs are isomorphic. If the vertex labelling is transferred from the common underlying graph, then \dot{G} is switching equivalent to \dot{H} if and only if there is a diagonal matrix S of ± 1 s, called the *switching matrix*, such that $A_{\dot{H}} = S^{-1}A_{\dot{G}}S$.
- In this case, we also have $L_{\dot{H}} = S^{-1}L_{\dot{G}}S$. Switching equivalence preserves the spectrum of $A_{\dot{G}}$ and the spectrum of $L_{\dot{G}}$.
- If **x** is an eigenvector of $A_{\dot{G}}$ (or $L_{\dot{G}}$), then S**x** is an eigenvector that corresponds to the same eigenvalue of $A_{\dot{H}}$ (or $L_{\dot{H}}$).

- We say that an eigenvalue of $A_{\dot{G}}$ or $L_{\dot{G}}$ is *main* if the corresponding eigenspace contains an eigenvector that is non-orthogonal to the all-1 vector **j**. For example, for every unsigned graph *G*, zero is the Laplacian eigenvalue associated with **j**, and therefore zero is the main eigenvalue.
- It was proved that for every eigenvalue of a signed graph, there exists a switching equivalent signed graph in which this particular eigenvalue is main.
- Main eigenvalues are important for counting walks as well as for applications in control theory.

- In Akbari et al. conjectured that, apart from K₂ and the graph obtained by deleting an edge of K₄, for every graph G there exists a switching equivalent signed graph G such that all the eigenvalues of A_G are main. In the same reference, the conjecture is confirmed for graphs with at most 9 vertices and also for Cayley graphs, distance-regular graphs, vertex-transitive and edge-transitive graphs, double stars and paths.
- We consider an analogue problem for Laplacian spectrum of signed graphs.

Problem

For a given graph G determine all switching equivalent signed graphs \dot{G} such that all the eigenvalues of $A_{\dot{G}}$ (or $L_{\dot{G}}$) are main.

We use **s** to denote the vector equal to the main diagonal of the switching matrix S. We say that the pair (A_G, \mathbf{s}) (or (L_G, \mathbf{s})) is *mainable* if all the eigenvalues of $S^{-1}A_GS$ (or $S^{-1}L_GS$) are main.

Let G and H be the graphs with Laplacian eigenvalues $\lambda_1, \lambda_2, \ldots, \lambda_m = 0$ and $\mu_1, \mu_2, \ldots, \mu_n = 0$, respectively. The Laplacian eigenvalues of $G \nabla H$ are m + n, $\lambda_1 + n$, $\lambda_2 + n$, $\ldots, \lambda_{m-1} + n$, $\mu_1 + m$, $\mu_2 + m$, $\ldots, \mu_{n-1} + m$ and 0.

If **x** is a Laplacian eigenvector of *G* orthogonal to **j** with a Laplacian eigenvalue λ , then its extension being zero on each vertex of *H* is a Laplacian eigenvector of $G\nabla H$ with eigenvalue $\lambda + n$, and similarly for the Laplacian eigenvectors of $G\nabla H$ that are formed on the basis of those of *H*. The Laplacian eigenvalue m + n corresponds to the eigenvector with weight *m* on each vertex of *G* and -n on each vertex of *H*.

If G is a graph with $n \ (n \ge 6)$ vertices, then

(i) G realizes $S_{1,n}$ if and only if

(a) $G \cong (2K_1) \nabla (K_1 \cup H)$, for some graph H that realizes $S_{n-4,n-3}$ or

(b) $G \cong K_1 \nabla H$, for some graph H that realizes $S_{n-1,n-1}$;

(ii) G realizes
$$S_{n-1,n}$$
 if and only if

(a) $G \cong K_1 \nabla (K_2 \cup H)$, for some graph H that realizes $S_{2,n-3}$ or

- (b) $G \cong K_1 \nabla (K_1 \cup H)$, for some graph H that realizes $S_{n-2,n-2}$;
- (iii) If $2 \le i \le n-2$, then G realizes $S_{i,n}$ if and only if $G \cong K_1 \nabla (K_1 \cup H)$, for some graph H that realizes $S_{i-1,n-2}$.

$$S_{i,n} = \{0, 1, \ldots, n\} \setminus \{i\}$$

- A *cograph* is a graph that does not contain the 4-vertex path *P*₄ as an induced subgraph.
- A threshold graph does not contain an induced subgraph isomorphic to the two copies of K_2 , or the path P_4 , or the cycle C_4 (we say that a threshold graph is $\{2K_2, P_4, C_4\}$ -free).
- A cograph has the form *G* ∪ *H* or *G*∇*H*, where *G*, *H* are also cographs. It follows that the Laplacian spectrum of a cograph is integral.

Lemma 1

If $G \ncong K_1$ is a cograph without repeated eigenvalues, then either $G \cong K_2$ or G is constructed as in item (i.a), (ii.a) or (iii) of Theorem 2.

Lemma 2

Let G be a cograph that realizes $S_{1,n}$. Then $G \cong K_1$, $G \cong K_2$, $G \cong (2K_1)\nabla(K_1 \cup K_2)$, $G \cong (2K_1)\nabla(K_1 \cup P_3)$ or G is formed by taking a cograph that realizes $S_{1,n-8}$ and applying (iii), (ii.a) and (i.a) of Theorem 2, respectively.

Lemma 3

Let G be a cograph that realizes $S_{n-1,n}$. Then $G \cong K_2$, $G \cong P_3$, $G \cong K_1 \nabla (K_2 \cup P_3)$, $G \cong K_1 \nabla (K_2 \cup K_1 \nabla (K_1 \cup K_2))$ or G is formed by taking a cograph that realizes $S_{n-9,n-8}$ and applying (i.a), (iii) and (ii.a) of Theorem 2, respectively.

Lemma 4

Let G be a cograph that realizes $S_{i,n}$, for $2 \le i \le n-2$. Then G is formed by applying (iii) of Theorem 2 to a cograph that realizes $S_{i-1,n-2}$.

Lemma 5

There is a cograph G that realizes $S_{i,n}$ if and only if

- (i) i = 1 with $n \equiv 1$ or $n \equiv 2 \pmod{4}$ or i = n 1 with $n \equiv 2$ or $n \equiv 3 \pmod{4}$ or,
- (ii) $2 \le i \le n-2$ and either $n \equiv 2i 1$ or $n \equiv 2i \pmod{4}$.

Moreover, in each case, G is uniquely determined by the given spectrum.

Let G be a cograph realizing $S_{1,n}$ which is obtained as in Lemma 2 from a cograph $H \not\cong K_1$ that realizes $S_{1,n-8}$. Let $\mathbf{s} = (s_1, s_2, \ldots, s_n)^T$ be a (1, -1)-vector and $\mathbf{s}' = (s_9, s_{10}, \ldots, s_n)^T$ be the restriction of \mathbf{s} (on H). If (L_H, \mathbf{s}') is mainable, then (L_G, \mathbf{s}) is mainable if and only if $\langle \mathbf{s}, \mathbf{j} \rangle \neq 0$, $s_1 \neq s_2$, $s_5 \neq s_6$, $-\langle \mathbf{s}', \mathbf{j_{n-8}} \rangle \notin \{s_7 + s_8, s_3 + s_4 + s_7 + s_8\}$.

Theorem 4

Let G be a cograph realizing $S_{n-1,n}$ which is obtained as in Lemma 3 from a cograph H that realizes $S_{n-9,n-8}$. Let $\mathbf{s} = (s_1, s_2, \dots, s_n)^T$ be a (1, -1)-vector and $\mathbf{s}' = (s_9, s_{10}, \dots, s_n)^T$ be the restriction of \mathbf{s} . If (L_H, \mathbf{s}') is mainable, then (L_G, \mathbf{s}) is mainable if and only if $\langle \mathbf{s}, \mathbf{j} \rangle \neq 0$, $s_2 \neq s_3$, $s_6 \neq s_7$, $-\langle \mathbf{s}', \mathbf{j_{n-8}} \rangle \notin \{s_8, s_4 + s_5 + s_8\}$.

Mainability of cographs

Theorem 5

Let G be a cograph realizing $S_{i,n}$, for $2 \le i \le n-2$, which is obtained as in Lemma 4 from a cograph H that realizes $S_{i-1,n-2}$. A complete system of linearly independent eigenvectors of G is

$$\begin{bmatrix} 1 & 0 & 0 & \cdots & 0 & 0 & 1 \\ 1 & 0 & 0 & \cdots & 0 & 1 & -\frac{1}{n-1} \\ \mathbf{j} & \mathbf{y}_1 & \mathbf{y}_2 & \cdots & \mathbf{y}_{n-3} & -\frac{1}{n-2}\mathbf{j} & -\frac{1}{n-1}\mathbf{j} \end{bmatrix},$$

where $y_1, y_2, \ldots, y_{n-3}$ are linearly independent eigenvectors corresponding to non-zero eigenvalues of H.

Let $\mathbf{s} = (s_1, s_2, \dots, s_n)^{\mathsf{T}}$ be a (1, -1)-vector and $\mathbf{s}' = (s_3, s_4, \dots, s_n)^{\mathsf{T}}$ be the restriction of \mathbf{s} . If (L_H, \mathbf{s}') is mainable, then (L_G, \mathbf{s}) is mainable if and only if $\langle \mathbf{s}, \mathbf{j} \rangle \neq 0$.

A graph G is a threshold graph without repeated eigenvalues if and only if G realizes $S_{i,n}$, where n = 2i - 1 or n = 2i and $i \in \mathbb{N}$. Moreover, with an appropriate vertex labelling, linearly independent eigenvectors of G are given by the columns of

$$\begin{bmatrix} 1 & 0 & 0 & \cdots & 0 & 0 & 1 \\ 1 & 0 & 0 & \cdots & 0 & 1 & -\frac{1}{n-1} \\ 1 & 0 & 0 & \cdots & 1 & -\frac{1}{n-2} & -\frac{1}{n-1} \\ 1 & 0 & 0 & \cdots & -\frac{1}{n-3} & -\frac{1}{n-2} & -\frac{1}{n-1} \\ \vdots & \vdots & \vdots & \cdots & \vdots & \vdots & \vdots \\ 1 & 0 & 1 & \cdots & -\frac{1}{n-3} & -\frac{1}{n-2} & -\frac{1}{n-1} \\ 1 & 1 & -\frac{1}{2} & \cdots & -\frac{1}{n-3} & -\frac{1}{n-2} & -\frac{1}{n-1} \\ 1 & -1 & -\frac{1}{2} & \cdots & -\frac{1}{n-3} & -\frac{1}{n-2} & -\frac{1}{n-1} \end{bmatrix}.$$

If $\mathbf{s} = (s_1, s_2, \dots, s_n)^{\mathsf{T}}$ is a (1, -1)-vector, then (L_G, \mathbf{s}) is mainable if and only if $\langle \mathbf{s}, \mathbf{j} \rangle \neq 0$ and $s_{n-1} \neq s_n$.

(1)

Let G and H be graphs of order n_1 and n_2 $(n_1, n_2 \ge 2)$.

- Applications in control theory. For a symmetric n × n matrix M and an n × 1 vector b, we say that a pair (M, b) is controllable if every eigenvector of M is non-orthogonal to b. It is known that if M has an eigenvalue of multiplicity at least two, then (M, b) is not controllable for any choice of b.
- There is a particular case when we say that a signed graph G is controllable if A_G has no eigenvector orthogonal to j, and similarly it is called Laplacian controllable if the same holds for the Laplacian matrix L_G instead of A_G. Equivalently, a signed graph is (Laplacian) controllable if all its (Laplacian) eigenvalues are simple and main.

- It can be of the interest to study mainability of some other classes of graphs.
- Mainability regarding the adjacency spectrum.

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Thank you!